Dual supply translating transceiver; auto direction sensing; 3-state

Rev. 2 — 4 April 2024

Product data sheet

1. General description

The NXB0106-Q100 is an 6-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two 6-bit input-output ports (An and Bn), one output enable input (OE) and two supply pins ($V_{CC(A)}$ and $V_{CC(B)}$). $V_{CC(A)}$ can be supplied at any voltage between 1.2 V and 3.6 V and $V_{CC(B)}$ can be supplied at any voltage between 1.65 V and 5.5 V, making the device suitable for translating between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V).

Pins An and OE are referenced to $V_{CC(A)}$ and pins Bn are referenced to $V_{CC(B)}$. A LOW level at pin OE causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using I_{OFF} . The I_{OFF} circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 1) and is suitable for use in automotive applications.

2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 1)
 Specified from -40 °C to +85 °C and from -40 °C to +125 °C
- Wide supply voltage range:
 - V_{CC(A)}: 1.2 V to 3.6 V and V_{CC(B)}: 1.65 V to 5.5 V
- I_{OFF} circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
 - HBM: ANSI/ESDA/JEDEC JS-001 class 2 exceeds 2500 V for A port
 - HBM: ANSI/ESDA/JEDEC JS-001 class 3B exceeds 15000 V for B port
 - CDM: ANSI/ESDA/JEDEC JS-002 class C3 exceeds 1500 V
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- DHVQFN package with Side-Wettable Flanks enabling Automatic Optical Inspection (AOI) of solder joints

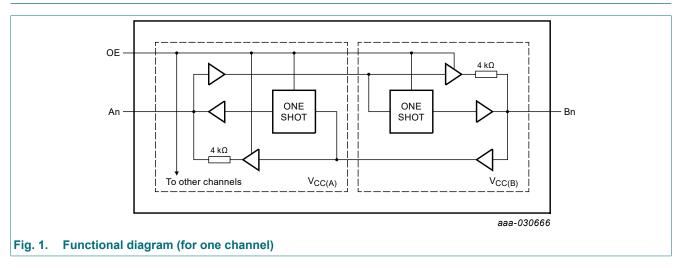
3. Ordering information

Table 1. Ordering information

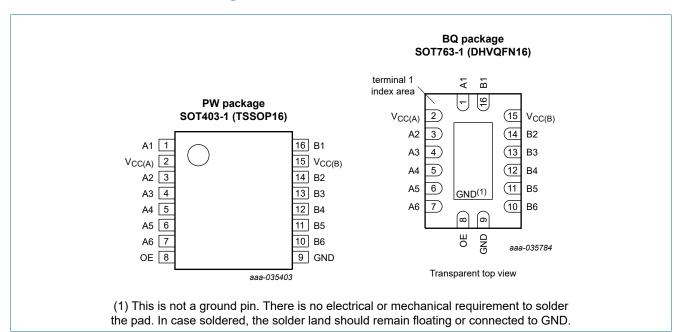
| Type number | Package | | | | | | | | |
|----------------|-------------------|----------|--------------------------------------------------------------------------------------------------------------------------------------|-----------------|--|--|--|--|--|
| | Temperature range | Name | Description | Version | | | | | |
| NXB0106PW-Q100 | −40 °C to +125 °C | TSSOP16 | plastic thin shrink small outline package; 16 leads; body width 4.4 mm | <u>SOT403-1</u> | | | | | |
| NXB0106BQ-Q100 | −40 °C to +125 °C | DHVQFN16 | plastic dual in-line compatible thermal enhanced very thin quad flat package; no leads; 16 terminals; body 2.5 × 3.5 × 0.85 mm | <u>SOT763-1</u> | | | | | |

ne<mark>x</mark>peria

4. Functional diagram



5. Pinning information



5.1. Pinning

5.2. Pin description

| Table 2. Pin description | | |
|--------------------------|------------------------|----------------------------------------------------------------------------|
| Symbol | Pin | Description |
| A1, A2, A3, A4, A5, A6 | 1, 3, 4, 5, 6, 7 | data input or output (referenced to $V_{CC(A)}$) |
| V _{CC(A)} | 2 | supply voltage A |
| OE | 8 | output enable input (active HIGH; referenced to $V_{\text{CC}(\text{A})})$ |
| GND | 9 | ground (0 V) |
| B1, B2, B3, B4, B5, B6 | 16, 14, 13, 12, 11, 10 | data input or output (referenced to $V_{CC(B)}$) |
| V _{CC(B)} | 15 | supply voltage B |

6. Functional description

Table 3. Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

| Supply voltage | | Input | Input/output | |
|---------------------------------------|-----------------|-------|-----------------|-----------------|
| V _{CC(A)} V _{CC(B)} | | OE | An | Bn |
| 1.2 V to V _{CC(B)} | 1.65 V to 5.5 V | L | Z | Z |
| 1.2 V to V _{CC(B)} | 1.65 V to 5.5 V | Н | input or output | output or input |
| GND[1] | GND[1] | Х | Z | Z |

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | | Min | Max | Unit |
|--------------------|-------------------------|------------------------------------------|-------------|------|------------------------|------|
| V _{CC(A)} | supply voltage A | | | -0.5 | +6.5 | V |
| V _{CC(B)} | supply voltage B | | | -0.5 | +6.5 | V |
| VI | input voltage | | [1] | -0.5 | +6.5 | V |
| Vo | output voltage | Active mode | [1] [2] [3] | -0.5 | V _{CCO} + 0.5 | V |
| | | Power-down or 3-state mode | [1] | -0.5 | +6.5 | V |
| I _{IK} | input clamping current | V ₁ < 0 V | | -50 | - | mA |
| I _{OK} | output clamping current | V _O < 0 V | | -50 | - | mA |
| I _O | output current | $V_{O} = 0 V$ to V_{CCO} | [2] | - | ±50 | mA |
| I _{CC} | supply current | I _{CC(A)} or I _{CC(B)} | | - | 100 | mA |
| I _{GND} | ground current | | | -100 | - | mA |
| T _{stg} | storage temperature | | | -65 | +150 | °C |
| P _{tot} | total power dissipation | T _{amb} = -40 °C to +125 °C | [4] | - | 500 | mW |

[1] The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

[2] V_{CCO} is the supply voltage associated with the output.

[3] V_{CCO} + 0.5 V should not exceed 6.5 V.

[4] For SOT403-1 (TSSOP16) package: P_{tot} derates linearly with 8.5 mW/K above 91 °C.

For SOT763-1 (DHVQFN16) package: P_{tot} derates linearly with 11.2 mW/K above 106 °C.

8. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Max | Unit |
|--------------------|-------------------------------------|-----------------------------------------------------------------------------------------------------------------|------|------|------|
| V _{CC(A)} | supply voltage A | | 1.2 | 3.6 | V |
| V _{CC(B)} | supply voltage B | | 1.65 | 5.5 | V |
| VI | input voltage | | 0 | 5.5 | V |
| Vo | output voltage | Power-down or 3-state mode; $V_{CC(A)} = 1.2 V \text{ to } 3.6 V;$ $V_{CC(B)} = 1.65 V \text{ to } 5.5 V$ | | | |
| | | A port | 0 | 3.6 | V |
| | | B port | 0 | 5.5 | V |
| T _{amb} | ambient temperature | | -40 | +125 | °C |
| Δt/ΔV | input transition rise and fall rate | $V_{CC(A)} = 1.2 V \text{ to } 3.6 V;$ $V_{CC(B)} = 1.65 V \text{ to } 5.5 V$ | - | 40 | ns/V |

Table 5. Recommended operating conditions [1] [2]

[1] The A and B sides of an unused I/O pair must be held in the same state, both at V_{CCI} or both at GND.

[2] $V_{CC(A)}$ must be less than or equal to $V_{CC(B)}$.

9. Static characteristics

Table 6. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T_{amb} = 25 °C.

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|------------------|------------------------------|-------------------------------------------------------------------------------------------------------------------------|-----|------|-----|------|
| V _{OH} | HIGH-level output voltage | A port; V _{CC(A)} = 1.2 V; I _O = -20 μA | - | 1.1 | - | V |
| V _{OL} | LOW-level output voltage | A port; V _{CC(A)} = 1.2 V; I _O = 20 μA | - | 0.09 | - | V |
| I _I | input leakage current | OE input; V _I = 0 V to 3.6 V; V _{CC(A)} = 1.2 V to 3.6 V; V _{CC(B)} = 1.65 V to 5.5 V | - | - | ±1 | μA |
| I _{OZ} | OFF-state output current | A or B port; $V_O = 0$ V to V_{CCO} ; $V_{CC(A)} = 1.2$ V to 3.6 V; [1] $V_{CC(B)} = 1.65$ V to 5.5 V | - | - | ±1 | μA |
| I _{OFF} | power-off leakage current | A port; V _I or V _O = 0 V to 3.6 V; V _{CC(A)} = 0 V; V _{CC(B)} = 0 V to 5.5 V | - | - | ±1 | μA |
| | | B port; V ₁ or V ₀ = 0 V to 5.5 V; V _{CC(B)} = 0 V; V _{CC(A)} = 0 V to 3.6 V | - | - | ±1 | μA |
| Cl | input capacitance | OE input; $V_{CC(A)}$ = 1.2 V to 3.6 V; $V_{CC(B)}$ = 1.65 V to 5.5 V | - | 5 | - | pF |
| C _{I/O} | input/output | A port; $V_{CC(A)}$ = 1.2 V to 3.6 V; $V_{CC(B)}$ = 1.65 V to 5.5 V | - | 5 | - | pF |
| | capacitance | B port; $V_{CC(A)}$ = 1.2 V to 3.6 V; $V_{CC(B)}$ = 1.65 V to 5.5 V | - | 8 | - | pF |

[1] V_{CCO} is the supply voltage associated with the output.

Table 7. Typical supply current

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T_{amb} = 25 °C.

| V _{CC(A)} | V _{CC(B)} | | | | | | | | |
|--------------------|--------------------|--------------------|--------------------|--------------------|--------------------|--------------------|--------------------|--------------------|----|
| | 1.8 V | | 2.5 | 2.5 V | | 3.3 V | | V | |
| | I _{CC(A)} | I _{CC(B)} | |
| 1.2 V | 10 | 10 | 10 | 10 | 10 | 20 | 10 | 1050 | nA |
| 1.5 V | 10 | 10 | 10 | 10 | 10 | 10 | 10 | 650 | nA |
| 1.8 V | 10 | 10 | 10 | 10 | 10 | 10 | 10 | 350 | nA |
| 2.5 V | - | - | 10 | 10 | 10 | 10 | 10 | 40 | nA |
| 3.3 V | - | - | - | - | 10 | 10 | 10 | 10 | nA |

Table 8. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | | -40 °C to | o +85 °C | -40 °C to | +125 °C | Unit |
|------------------|-----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----|------------------------|----------------------|------------------------|----------------------|------|
| | | | | Min | Max | Min | Мах | 1 |
| VIH | HIGH-level | A or B port and OE input | [1] | | | | | |
| | input voltage | V _{CC(A)} = 1.2 V to 3.6 V; V _{CC(B)} = 1.65 V to 5.5 V | | 0.65V _{CCI} | - | 0.65V _{CCI} | - | V |
| V _{IL} | LOW-level | A or B port and OE input | [1] | | | | | |
| | input voltage | V _{CC(A)} = 1.2 V to 3.6 V; V _{CC(B)} = 1.65 V to 5.5 V | | - | 0.35V _{CCI} | - | 0.35V _{CCI} | V |
| V _{OH} | HIGH-level | A or B port; I _O = -20 μA | [2] | | | | | |
| | output voltage | A port; V _{CC(A)} = 1.4 V to 3.6 V | | V _{CCO} - 0.4 | - | V _{CCO} - 0.4 | - | V |
| | | B port; $V_{CC(B)}$ = 1.65 V to 5.5 V | | V _{CCO} - 0.4 | - | V _{CCO} - 0.4 | - | V |
| V _{OL} | LOW-level | A or B port; I _O = 20 μA | [2] | | | | | |
| | output voltage | A port; V _{CC(A)} = 1.4 V to 3.6 V | | - | 0.4 | - | 0.4 | V |
| | | B port; V _{CC(B)} = 1.65 V to 5.5 V | | - | 0.4 | - | 0.4 | V |
| I | input leakage current | $\begin{array}{l} \text{OE input; V}_{I} = 0 \text{ V to } 3.6 \text{ V;} \\ \text{V}_{\text{CC}(A)} = 1.2 \text{ V to } 3.6 \text{ V;} \\ \text{V}_{\text{CC}(B)} = 1.65 \text{ V to } 5.5 \text{ V} \end{array}$ | | - | ±2 | - | ±5 | μA |
| I _{OZ} | OFF-state output current | A or B port; $V_O = 0 V \text{ or } V_{CCO}$; $V_{CC(A)} = 1.2 V \text{ to } 3.6 V$; $V_{CC(B)} = 1.65 V \text{ to } 5.5 V$ | [2] | - | ±2 | - | ±10 | μA |
| I _{OFF} | power-off leakage | A port; V ₁ or V ₀ = 0 V to 3.6 V; V _{CC(A)} = 0 V; V _{CC(B)} = 0 V to 5.5 V | | - | ±2 | - | ±10 | μA |
| | current | B port; V _I or V _O = 0 V to 5.5 V; V _{CC(B)} = 0 V; V _{CC(A)} = 0 V to 3.6 V | | - | ±2 | - | ±10 | μA |

| Symbol | Parameter | Conditions | -40 °C t | to +85 °C | -40 °C to | o +125 °C | Unit |
|-----------------|----------------|--------------------------------------------------------------------------------------------|----------|-----------|-----------|-----------|------|
| | | - | Min | Max | Min | Max | |
| I _{CC} | supply current | $V_{I} = 0 V \text{ or } V_{CCI}; I_{O} = 0 A$ [1] | | | | | |
| | | I _{CC(A)} | | | | | |
| | | OE = LOW; V _{CC(A)} = 1.4 V to 3.6 V; V _{CC(B)} = 1.65 V to 5.5 V | - | 4.3 | - | 15 | μA |
| | | OE = HIGH; V _{CC(A)} = 1.4 V to 3.6 V; V _{CC(B)} = 1.65 V to 5.5 V | - | 4.3 | - | 20 | μA |
| | | V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V | - | 1.7 | - | 15 | μA |
| | | V _{CC(A)} = 0 V; V _{CC(B)} = 5.5 V | - | -1.7 | - | -15 | μA |
| | | I _{CC(B)} | | | | | |
| | | OE = LOW; V _{CC(A)} = 1.4 V to 3.6 V; V _{CC(B)} = 1.65 V to 5.5 V | - | 4.3 | - | 20 | μA |
| | | OE = HIGH; V _{CC(A)} = 1.4 V to 3.6 V; V _{CC(B)} = 1.65 V to 5.5 V | - | 11.1 | - | 65 | μA |
| | | V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V | - | -1.7 | - | -15 | μA |
| | | V _{CC(A)} = 0 V; V _{CC(B)} = 5.5 V | - | 1.7 | - | 15 | μA |
| | | $I_{CC(A)} + I_{CC(B)}$ | | | | | |
| | | $V_{CC(A)} = 1.4 V \text{ to } 3.6 V;$ $V_{CC(B)} = 1.65 V \text{ to } 5.5 V$ | - | 12.8 | - | 70 | μA |

Dual supply translating transceiver; auto direction sensing; 3-state

 V_{CCI} is the supply voltage associated with the input. V_{CCO} is the supply voltage associated with the output. [1]

[2]

10. Dynamic characteristics

Table 9. Typical dynamic characteristics for temperature 25 °C [1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 4; for waveforms see Fig. 2 and Fig. 3.

| Symbol | Parameter | Conditions | | Vc | С(В) | | Unit |
|--------------------|---------------------------------|-------------------------------|-------|-------|-------|-------|----------|
| | | | 1.8 V | 2.5 V | 3.3 V | 5.0 V | |
| $V_{CC(A)} = -$ | 1.2 V; T _{amb} = 25 °C | · · · | | | | 1 | I |
| t _{pd} | propagation delay | A to B | 6.9 | 5.6 | 5.1 | 4.9 | ns |
| | B to A | 7.1 | 5.8 | 5.0 | 5.1 | ns | |
| t _{en} | enable time | OE to A, B | 500 | 500 | 500 | 500 | ns |
| t _{dis} | disable time | OE to A; no external load [2] | 14.5 | 14.5 | 14.5 | 14.5 | ns |
| | | OE to B; no external load [2] | 12.2 | 10.1 | 9.3 | 8.7 | ns |
| | | OE to A; see Fig. 3 | 87 | 87 | 87 | 87 | ns |
| | | OE to B; see Fig. 3 | 98 | 71 | 101 | 68 | ns |
| t _t | transition time | A port | 4.2 | 4.2 | 4.2 | 4.2 | ns |
| | | B port | 2.7 | 2.0 | 1.7 | 1.5 | ns |
| t _{sk(o)} | output skew time | between channels [3] | 1.4 | 0.7 | 0.6 | 0.5 | ns |
| t _W | pulse width | data inputs | 13 | 13 | 13 | 13 | ns |
| f _{data} | data rate | | 60 | 60 | 60 | 60 | Mbps |

[1] t_{pd} is the same as t_{PLH} and t_{PHL} .

 t_{en} is the same as t_{PZL} and $t_{\text{PZH}}.$

 t_{dis} is the same as t_{PLZ} and $t_{\text{PHZ}}.$

 t_t is the same as t_{THL} and $t_{TLH}.$

[2] These values are guaranteed by design.

[3] Skew between any two outputs of the same package switching in the same direction.

Table 10. Dynamic characteristics for temperature range -40 °C to +85 °C [1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 4; for waveforms see Fig. 2 and Fig. 3.

| Symbol | Parameter | Conditions | V _{CC(B)} | | | | | | | Unit | |
|----------------------|---------------------|-------------------------------|--------------------|----------|---------|---------|-----|------|---------|---------|------|
| | | | 1.8 V ± | : 0.15 V | 2.5 V : | ± 0.2 V | | | 5.0 V : | ± 0.5 V | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| V _{CC(A)} = | 1.5 V ± 0.1 V | | | | | | | | | | |
| t _{pd} | propagation | A to B | 1.4 | 11.4 | 1.2 | 8.0 | 1.1 | 6.7 | 0.8 | 6.2 | ns |
| | delay | B to A | 0.9 | 10.8 | 0.7 | 8.3 | 0.4 | 7.8 | 0.3 | 7.2 | ns |
| t _{en} | enable time | OE to A, B | - | 1.0 | - | 1.0 | - | 1.0 | - | 1.0 | μs |
| t _{dis} | disable time | OE to A; no external load [2] | 3.4 | 18.0 | 3.4 | 18.0 | 3.4 | 18.0 | 3.4 | 18.0 | ns |
| | | OE to B; no external load [2] | 3.4 | 19.5 | 3.4 | 15.0 | 2.8 | 13.0 | 1.6 | 11.5 | ns |
| | | OE to A; see Fig. 3 | - | 100 | - | 100 | - | 100 | - | 100 | ns |
| | | OE to B; see Fig. 3 | - | 150 | - | 105 | - | 150 | - | 105 | ns |
| t _t | transition | A port | 0.8 | 6.5 | 0.8 | 6.3 | 0.8 | 6.3 | 0.8 | 6.3 | ns |
| | time | B port | 1.0 | 7.3 | 0.7 | 4.9 | 0.7 | 4.6 | 0.6 | 4.6 | ns |
| t _{sk(o)} | output skew time | between channels [3] | - | 2.6 | - | 1.9 | - | 1.6 | - | 1.3 | ns |
| t _W | pulse width | data inputs | 20 | - | 20 | - | 20 | - | 20 | - | ns |
| f _{data} | data rate | | - | 50 | - | 50 | - | 50 | - | 50 | Mbps |

Dual supply translating transceiver; auto direction sensing; 3-state

| Symbol | Parameter | Conditions | | | | Vcc | (В) | | | | Unit |
|--------------------|---------------------|-------------------------------|---------|----------|---------|---------|---------|---------|---------|---------|------|
| | | | 1.8 V ± | : 0.15 V | 2.5 V : | ± 0.2 V | 3.3 V : | ± 0.3 V | 5.0 V : | ± 0.5 V | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| $V_{CC(A)} = -$ | 1.8 V ± 0.15 V | | | | | | | | | | |
| t _{pd} | propagation | A to B | 1.6 | 10.8 | 1.4 | 7.9 | 1.3 | 6.2 | 1.2 | 5.3 | ns |
| | delay | B to A | 1.5 | 9.2 | 1.3 | 7.2 | 0.8 | 6.3 | 0.5 | 5.8 | ns |
| t _{en} | enable time | OE to A, B | - | 1.0 | - | 1.0 | - | 1.0 | - | 1.0 | μs |
| t _{dis} | disable time | OE to A; no external load [2] | 2.7 | 13.0 | 2.7 | 13.0 | 2.7 | 13.0 | 2.7 | 13.0 | ns |
| | | OE to B; no external load [2] | 3.7 | 18.0 | 2.8 | 13.0 | 2.3 | 11.5 | 1.4 | 9.5 | ns |
| | | OE to A; see Fig. 3 | - | 120 | - | 120 | - | 120 | - | 120 | ns |
| | | OE to B; see Fig. 3 | - | 150 | - | 105 | - | 150 | - | 105 | ns |
| tt | transition | A port | 0.7 | 5.1 | 0.7 | 5.0 | 1.0 | 5.0 | 0.7 | 5.0 | ns |
| | time | B port | 1.0 | 7.3 | 0.7 | 5.0 | 0.7 | 3.9 | 0.6 | 3.8 | ns |
| t _{sk(o)} | output skew time | between channels [3] | - | 0.8 | - | 0.7 | - | 0.6 | - | 0.6 | ns |
| t _W | pulse width | data inputs | 19 | - | 17 | - | 17 | - | 17 | - | ns |
| f _{data} | data rate | | - | 52 | - | 60 | - | 60 | - | 60 | Mbps |
| $V_{CC(A)} = 2$ | 2.5 V ± 0.2 V | | 1 | | 1 | 1 | 1 | 1 | | 1 | 1 |
| t _{pd} | propagation | A to B | - | - | 1.1 | 7.5 | 1.0 | 5.2 | 0.9 | 4.2 | ns |
| | delay | B to A | - | - | 1.0 | 5.6 | 0.6 | 5.0 | 0.3 | 4.2 | ns |
| t _{en} | enable time | OE to A, B | - | - | - | 1.0 | - | 1.0 | - | 1.0 | μs |
| t _{dis} | disable time | OE to A; no external load [2] | - | - | 2.3 | 8.0 | 2.3 | 8.0 | 2.3 | 8.0 | ns |
| | | OE to B; no external load [2] | - | - | 1.8 | 11.5 | 2.5 | 9.5 | 1.1 | 8.0 | ns |
| | | OE to A; see Fig. 3 | - | - | - | 85 | - | 85 | - | 85 | ns |
| | | OE to B; see Fig. 3 | - | - | - | 105 | - | 150 | - | 100 | ns |
| tt | transition | A port | - | - | 0.8 | 3.6 | 0.6 | 3.6 | 0.5 | 3.5 | ns |
| | time | B port | - | - | 0.6 | 4.9 | 0.7 | 3.9 | 0.6 | 3.2 | ns |
| t _{sk(o)} | output skew time | between channels [3] | - | - | - | 0.4 | - | 0.3 | - | 0.3 | ns |
| t _W | pulse width | data inputs | - | - | 13 | - | 10 | - | 10 | - | ns |
| f _{data} | data rate | | - | - | - | 80 | - | 100 | - | 100 | Mbps |

Dual supply translating transceiver; auto direction sensing; 3-state

| Symbol | Parameter | Conditions | | | | Vcc | ;(B) | | | | Unit |
|--------------------|---------------------|-------------------------------|---------|----------|---------|---------|---------|---------|---------|---------|------|
| | | | 1.8 V ± | : 0.15 V | 2.5 V : | ± 0.2 V | 3.3 V = | ± 0.3 V | 5.0 V : | ± 0.5 V | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| $V_{CC(A)} = 1$ | 3.3 V ± 0.3 V | - | | | | | | | | | |
| t _{pd} | propagation | A to B | - | - | - | - | 0.9 | 4.8 | 0.8 | 3.9 | ns |
| | delay | B to A | - | - | - | - | 0.5 | 4.3 | 0.2 | 3.7 | ns |
| t _{en} | enable time | OE to A, B | - | - | - | - | - | 1.0 | - | 1.0 | μs |
| t _{dis} | disable time | OE to A; no external load [2] | - | - | - | - | 1.9 | 6.5 | 1.8 | 6.5 | ns |
| | | OE to B; no external load [2] | - | - | - | - | 0.9 | 8.5 | 1.6 | 7.0 | ns |
| | | OE to A; see Fig. 3 | - | - | - | - | - | 125 | - | 125 | ns |
| | | OE to B; see Fig. 3 | - | - | - | - | - | 150 | - | 100 | ns |
| tt | transition | A port | - | - | - | - | 0.5 | 3.0 | 0.5 | 3.0 | ns |
| | time | B port | - | - | - | - | 0.7 | 3.9 | 0.6 | 3.2 | ns |
| t _{sk(o)} | output skew time | between channels [3] | - | - | - | - | - | 0.4 | - | 0.3 | ns |
| t _W | pulse width | data inputs | - | - | - | - | 9.0 | - | 9.0 | - | ns |
| f _{data} | data rate | | - | - | - | - | - | 110 | - | 110 | Mbps |

 $\label{eq:tpd} [1] \quad t_{pd} \text{ is the same as } t_{PLH} \text{ and } t_{PHL}.$

 t_{en} is the same as t_{PZL} and $t_{\text{PZH}}.$

 t_{dis} is the same as t_{PLZ} and $t_{\text{PHZ}}.$

t_t is the same as t_{THL} and t_{TLH}. These values are guaranteed by design.

[2] These values are guaranteed by design.[3] Skew between any two outputs of the same package switching in the same direction.

Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C [1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 4; for waveforms see Fig. 2 and Fig. 3.

| Cumple of | Deveneter | Conditions | | | · | V | | - | | Unit | |
|--------------------|---------------------|-------------------------------|---------|----------|---------|---------|---------|---------|---------|---------|------|
| Symbol | Parameter | | | | | | (В) | | | | _ |
| | | | 1.8 V ± | : 0.15 V | 2.5 V : | ± 0.2 V | 3.3 V : | ± 0.3 V | 5.0 V : | ± 0.5 V | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| $V_{CC(A)} =$ | 1.5 V ± 0.1 V | | | - | | | | | | | |
| t _{pd} | propagation | A to B | 1.4 | 11.9 | 1.2 | 9.0 | 1.1 | 7.3 | 0.8 | 6.5 | ns |
| | delay | B to A | 0.9 | 10.9 | 0.7 | 8.8 | 0.4 | 7.9 | 0.3 | 7.7 | ns |
| t _{en} | enable time | OE to A, B | - | 1.0 | - | 1.0 | - | 1.0 | - | 1.0 | μs |
| t _{dis} | disable time | OE to A; no external load [2] | 3.4 | 19.0 | 3.4 | 19.0 | 3.4 | 19.0 | 3.4 | 19.0 | ns |
| | | OE to B; no external load [2] | 3.4 | 22.0 | 3.4 | 16.0 | 2.8 | 14.0 | 1.6 | 12.5 | ns |
| | | OE to A; see Fig. 3 | - | 105 | - | 105 | - | 105 | - | 105 | ns |
| | | OE to B; see Fig. 3 | - | 155 | - | 110 | - | 155 | - | 105 | ns |
| t _t | transition | A port | 0.8 | 8.1 | 0.8 | 7.9 | 0.8 | 7.9 | 0.8 | 7.9 | ns |
| | time | B port | 1.0 | 9.1 | 0.7 | 6.1 | 0.7 | 5.8 | 0.6 | 5.8 | ns |
| t _{sk(o)} | output skew time | between channels [3] | - | 2.6 | - | 1.9 | - | 1.6 | - | 1.3 | ns |
| t _W | pulse width | data inputs | 25 | - | 25 | - | 25 | - | 25 | - | ns |
| f _{data} | data rate | | - | 40 | - | 40 | - | 40 | - | 40 | Mbps |

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Dual supply translating transceiver; auto direction sensing; 3-state

| Symbol | Parameter | Conditions | | | | Vcc | (В) | | | | Unit |
|----------------------------|---------------------|-------------------------------|---------|----------|---------|---------|---------|---------|-------|---------|------|
| | | | 1.8 V ± | ± 0.15 V | 2.5 V : | ± 0.2 V | 3.3 V : | ± 0.3 V | 5.0 V | ± 0.5 V | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| $V_{CC(A)} = -$ | 1.8 V ± 0.15 V | | | 1 | | | | | | | |
| t _{pd} | propagation | A to B | 1.6 | 11.1 | 1.4 | 8.1 | 1.3 | 6.5 | 1.2 | 5.5 | ns |
| | delay | B to A | 1.5 | 9.6 | 1.2 | 7.8 | 0.8 | 6.6 | 0.5 | 6.3 | ns |
| t _{en} | enable time | OE to A, B | - | 1.0 | - | 1.0 | - | 1.0 | - | 1.0 | μs |
| t _{dis} disable t | disable time | OE to A; no external load [2] | 2.7 | 14.0 | 2.7 | 14.0 | 2.7 | 14.0 | 2.7 | 14.0 | ns |
| | | OE to B; no external load [2] | 3.7 | 20.5 | 2.8 | 14.5 | 2.3 | 12.5 | 1.4 | 10.5 | ns |
| | | OE to A; see Fig. 3 | - | 125 | - | 125 | - | 125 | - | 125 | ns |
| | | OE to B; see Fig. 3 | - | 150 | - | 105 | - | 150 | - | 105 | ns |
| tt | transition | A port | 0.8 | 6.4 | 0.7 | 6.3 | 1.0 | 6.3 | 0.7 | 6.3 | ns |
| time | B port | 1.0 | 9.1 | 0.7 | 6.3 | 0.7 | 4.9 | 0.6 | 4.8 | ns | |
| t _{sk(o)} | output skew time | between channels [3] | - | 0.8 | - | 0.7 | - | 0.6 | - | 0.6 | ns |
| t _W | pulse width | data inputs | 22 | - | 18 | - | 18 | - | 18 | - | ns |
| f _{data} | data rate | | - | 45 | - | 55 | - | 55 | - | 55 | Mbps |
| $V_{CC(A)} = 2$ | 2.5 V ± 0.2 V | | 1 | | 1 | 1 | 1 | 1 | | 1 | 1 |
| t _{pd} | propagation | A to B | - | - | 1.1 | 7.6 | 1.0 | 5.8 | 0.9 | 4.4 | ns |
| | delay | B to A | - | - | 1.0 | 7.1 | 0.6 | 5.1 | 0.3 | 4.8 | ns |
| t _{en} | enable time | OE to A, B | - | - | - | 1.0 | - | 1.0 | - | 1.0 | μs |
| t _{dis} | disable time | OE to A; no external load [2] | - | - | 2.3 | 9.0 | 2.3 | 9.0 | 2.3 | 9.0 | ns |
| | | OE to B; no external load [2] | - | - | 1.8 | 13.0 | 2.6 | 10.5 | 1.1 | 8.5 | ns |
| | | OE to A; see Fig. 3 | - | - | - | 85 | - | 85 | - | 85 | ns |
| | | OE to B; see Fig. 3 | - | - | - | 105 | - | 150 | - | 100 | ns |
| t _t | transition | A port | - | - | 0.8 | 4.5 | 0.6 | 4.5 | 0.5 | 4.4 | ns |
| time | time | B port | - | - | 0.6 | 6.1 | 0.7 | 4.9 | 0.6 | 4.0 | ns |
| t _{sk(o)} | output skew time | between channels [3] | - | - | - | 0.4 | - | 0.3 | - | 0.3 | ns |
| t _W | pulse width | data inputs | - | - | 13 | - | 13 | - | 13 | - | ns |
| f _{data} | data rate | | - | - | - | 75 | - | 80 | - | 80 | Mbps |

Dual supply translating transceiver; auto direction sensing; 3-state

| Symbol | Parameter | Conditions | | | | Vcc | (В) | | | | Unit |
|--------------------|---------------------|-------------------------------|---------|----------|---------|---------|---------|---------|---------|---------|------|
| | | | 1.8 V ± | : 0.15 V | 2.5 V : | ± 0.2 V | 3.3 V : | ± 0.3 V | 5.0 V : | ± 0.5 V | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| $V_{CC(A)} = 1$ | 3.3 V ± 0.3 V | - | | | | | | | | | |
| t _{pd} | propagation | A to B | - | - | - | - | 0.9 | 5.3 | 0.8 | 4.2 | ns |
| | delay | B to A | - | - | - | - | 0.5 | 4.4 | 0.2 | 4.0 | ns |
| t _{en} | enable time | OE to A, B | - | - | - | - | - | 1.0 | - | 1.0 | μs |
| t _{dis} | disable time | OE to A; no external load [2] | - | - | - | - | 1.9 | 7.0 | 1.8 | 7.0 | ns |
| | | OE to B; no external load [2] | - | - | - | - | 0.9 | 9.5 | 1.6 | 7.5 | ns |
| | | OE to A; see Fig. 3 | - | - | - | - | - | 125 | - | 125 | ns |
| | | OE to B; see Fig. 3 | - | - | - | - | - | 150 | - | 100 | ns |
| tt | transition | A port | - | - | - | - | 0.5 | 3.8 | 0.5 | 3.8 | ns |
| | time | B port | - | - | - | - | 0.7 | 4.9 | 0.6 | 4.0 | ns |
| t _{sk(o)} | output skew time | between channels [3] | - | - | - | - | - | 0.4 | - | 0.3 | ns |
| t _W | pulse width | data inputs | - | - | - | - | 10 | - | 10 | - | ns |
| f _{data} | data rate | | - | - | - | - | - | 100 | - | 100 | Mbps |

[1] t_{pd} is the same as t_{PLH} and t_{PHL} .

 t_{en} is the same as t_{PZL} and $t_{\text{PZH}}.$

 t_{dis} is the same as t_{PLZ} and $t_{\text{PHZ}}.$

 t_{t} is the same as t_{THL} and $t_{\text{TLH}}.$

[2] These values are guaranteed by design.

[3] Skew between any two outputs of the same package switching in the same direction.

Table 12. Typical power dissipation capacitance [1] [2]

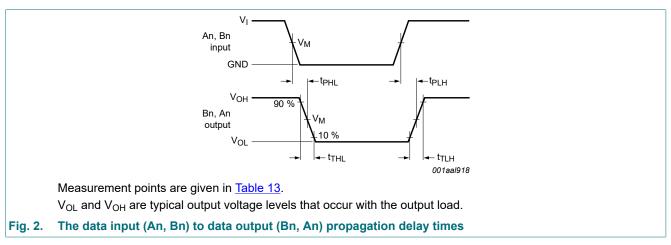
Voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | | | | Vc | C(A) | | | Unit |
|--------------------------------------|------------------------------------------|----------------------------|--------------------|-------|-------|-------|-------|-------|----------------|------|
| | | | 1.2 V | 1.2 V | 1.5 V | 1.8 V | 2.5 V | 2.5 V | 3.3 V | |
| | | | V _{CC(B)} | | | | | | | |
| | | | 1.8 V | 5.0 V | 1.8 V | 1.8 V | 2.5 V | 5.0 V | 3.3 V to 5.0 V | |
| T _{amb} = 2 | 5 °C | | | | | | | | | |
| C _{PD} power dissipation | outputs enabled; OE = V _{CC(A)} | | | | | | | | | |
| | dissipation capacitance | A port: (direction A to B) | 7.0 | 6.5 | 7.2 | 7.6 | 7.6 | 7.0 | 8.0 | pF |
| | | A port: (direction B to A) | 9.6 | 10.0 | 9.8 | 10.1 | 10.5 | 10.3 | 10.8 | pF |
| | | B port: (direction A to B) | 23.3 | 28.7 | 23.1 | 23.1 | 23.7 | 25.9 | 25.9 | pF |
| | | B port: (direction B to A) | 17.8 | 25.5 | 17.1 | 16.8 | 17.4 | 21.0 | 20.5 | pF |
| | | outputs disabled; OE = GND | | | | | | | | |
| | | A port: (direction A to B) | 0.2 | 0.2 | 0.2 | 0.3 | 0.3 | 0.3 | 0.3 | pF |
| | | A port: (direction B to A) | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | pF |
| | | B port: (direction A to B) | 0.01 | 0.02 | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 | pF |
| | | B port: (direction B to A) | 0.2 | 0.3 | 0.2 | 0.2 | 0.3 | 0.3 | 0.3 | pF |

[1] C_{PD} is used to determine the dynamic power dissipation (P_D in μ W). $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$ where: f_i = input frequency in MHz; f_o = output frequency in MHz;

 C_L = load capacitance in pF; V_{CC} = supply voltage in V;

N = number of inputs switching; $\Sigma(C_L \times V_{CC}^2 \times f_o)$ = sum of the outputs. [2] $f_i = 10 \text{ MHz}$; $V_i = \text{GND}$ to V_{CC} ; $t_r = t_f = 1 \text{ ns}$; $C_L = 0 \text{ pF}$; $R_L = \infty \Omega$.



10.1. Waveforms and test circuit

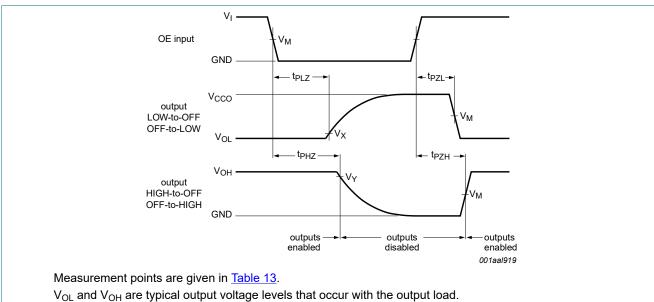


Fig. 3. 3-state enable and disable times

| Table 13. Measurement points [1] | | | | | | | | | |
|----------------------------------|---------------------|---------------------|--------------------------|--------------------------|--|--|--|--|--|
| Supply voltage | Input | Output | Output | | | | | | |
| V _{cco} | V _M | V _M | V _X | V _Y | | | | | |
| 1.2 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.1 V | V _{OH} - 0.1 V | | | | | |
| 1.5 V ± 0.1 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.1 V | V _{OH} - 0.1 V | | | | | |
| 1.8 V ± 0.15 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.15 V | V _{OH} - 0.15 V | | | | | |
| 2.5 V ± 0.2 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.15 V | V _{OH} - 0.15 V | | | | | |
| 3.3 V ± 0.3 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.3 V | V _{OH} - 0.3 V | | | | | |
| 5.0 V ± 0.5 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.3 V | V _{OH} - 0.3 V | | | | | |

[1] V_{CCI} is the supply voltage associated with the input and V_{CCO} is the supply voltage associated with the output.

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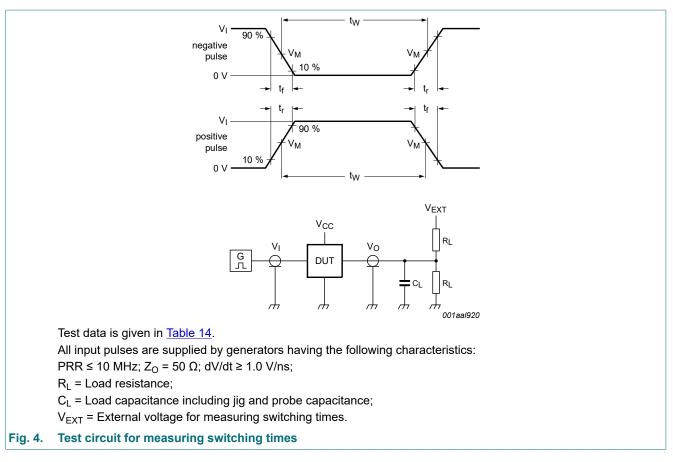


Table 14. Test data

| Supply voltag | Supply voltage | | | Load | | V _{EXT} | | |
|--------------------|--------------------|--------------------|------------|-------|--------------------|-------------------------------------|-------------------------------------|-----------------------------------------|
| V _{CC(A)} | V _{CC(B)} | V _I [1] | Δt/ΔV | CL | R _L [2] | t _{PLH} , t _{PHL} | t _{PZH} , t _{PHZ} | t _{PZL} , t _{PLZ} [3] |
| 1.2 V to 3.6 V | 1.65 V to 5.5 V | V _{CCI} | ≤ 1.0 ns/V | 15 pF | 50 kΩ, 1 MΩ | open | open | 2V _{CCO} |

[1] V_{CCI} is the supply voltage associated with the input.

[2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements, $R_L = 1 M\Omega$;

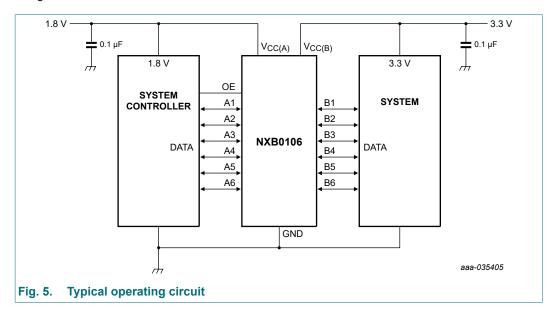
for measuring enable and disable times, $R_L = 50 \text{ k}\Omega$.

[3] V_{CCO} is the supply voltage associated with the output.

11. Application information

11.1. Applications

Voltage level-translation applications. The NXB0106-Q100 can be used to interface between devices or systems operating at different supply voltages. See <u>Fig. 5</u> for a typical operating circuit using the NXB0106-Q100.

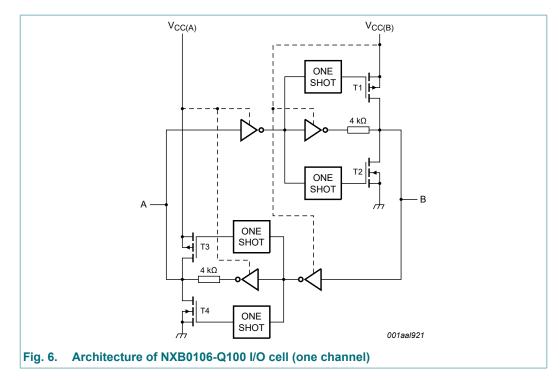


11.2. Architecture

The architecture of the NXB0106-Q100 is shown in Fig. 6. The device does not require an extra input signal to control the direction of data flow from A to B or from B to A. In a static state, the output drivers of the NXB0106-Q100 can maintain a defined output level, but the output architecture is designed to be weak, so that they can be overdriven by an external driver when data on the bus starts flowing in the opposite direction. The output one shots detect rising or falling edges on the A or B ports. During a rising edge, the one shots turn on the PMOS transistors (T1, T3) for a short duration, accelerating the low-to-high transition. Similarly, during a falling edge, the one shots turn on the NMOS transistors (T2, T4) for a short duration, accelerating the high-to-low transition. During output transitions the typical output impedance is 70 Ω at V_{CCO} = 1.2 V to 1.8 V, 50 Ω at V_{CCO} = 1.8 V to 3.3 V and 40 Ω at V_{CCO} = 3.3 V to 5.0 V.

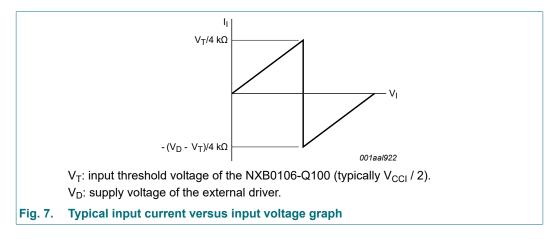
NXB0106_Q100

Dual supply translating transceiver; auto direction sensing; 3-state



11.3. Input driver requirements

For correct operation, the device driving the data I/Os of the NXB0106-Q100 must have a minimum drive capability of ± 2 mA. See Fig. 7 for a plot of typical input current versus input voltage.



11.4. Power up

During operation $V_{CC(A)}$ must never be higher than $V_{CC(B)}$, however during power-up $V_{CC(A)} \ge V_{CC(B)}$ does not damage the device, so either power supply can be ramped up first. There is no special power-up sequencing required. The NXB0106-Q100 includes circuitry that disables all output ports when either $V_{CC(A)}$ or $V_{CC(B)}$ is switched off.

11.5. Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = LOW causes all I/Os to assume the high-impedance OFF-state. The disable time (t_{dis} with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time (t_{en}) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

11.6. Pull-up or pull-down resistors on I/O lines

As mentioned previously the NXB0106-Q100 is designed with low static drive strength to drive capacitive loads of up to 70 pF. To avoid output contention issues, any pull-up or pull-down resistors used must be kept higher than 50 k Ω . For this reason the NXB0106-Q100 is not recommended for use in open drain driver applications such as 1-Wire or I²C. For these applications, the NXS0106-Q100 level translator is recommended.

12. Package outline

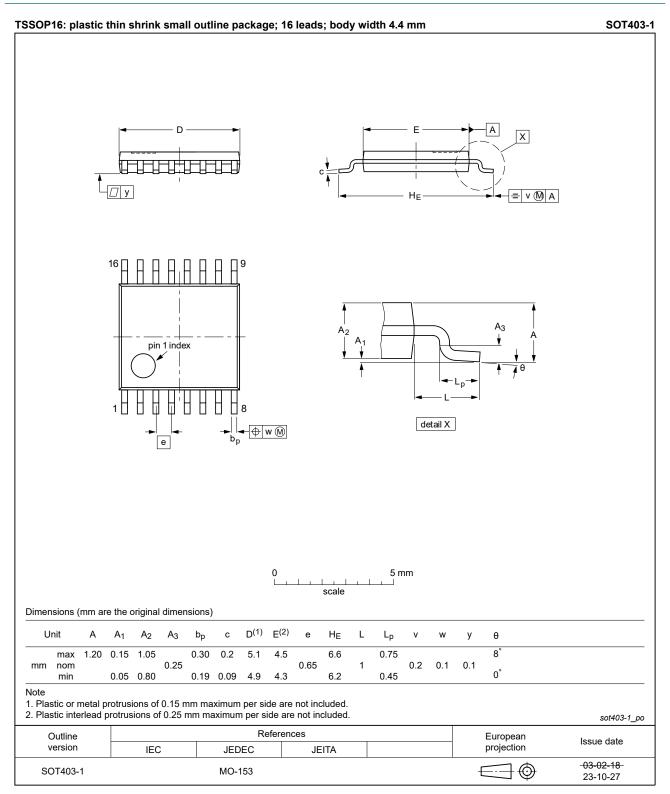


Fig. 8. Package outline SOT403-1 (TSSOP16)

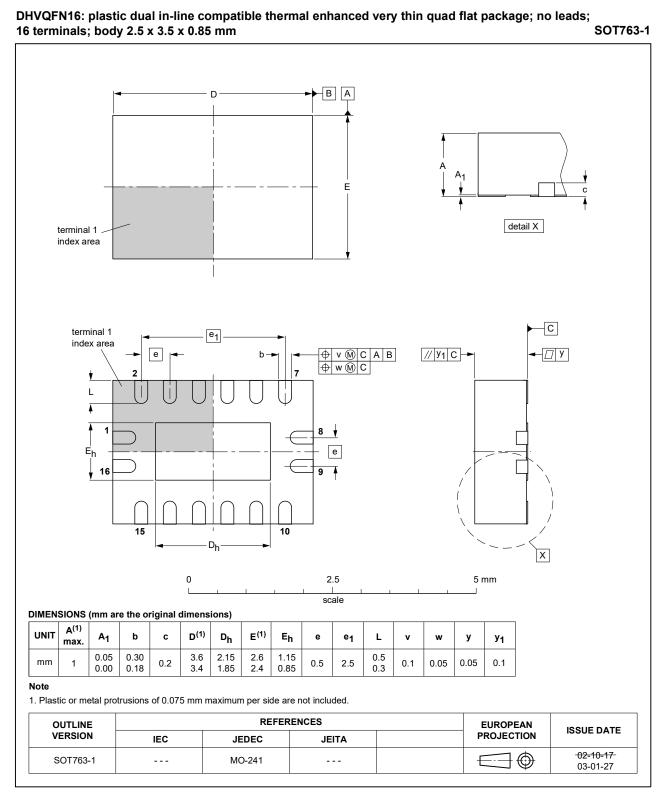


Fig. 9. Package outline SOT763-1 (DHVQFN16)

NXB0106_Q100

13. Abbreviations

| Acronym | Description |
|---------|-----------------------------------------|
| CDM | Charged Device Model |
| CMOS | Complementary Metal Oxide Semiconductor |
| DUT | Device Under Test |
| ESD | Electro Static Discharge |
| НВМ | Human Body Model |

14. Revision history

Table 16. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes | | | |
|------------------|------------------------------------------------------------------|--------------------|---------------|------------------|--|--|--|
| NXB0106_Q100 v.2 | 20240404 | Product data sheet | - | NXB0106_Q100 v.1 | | | |
| Modifications: | • Fig. 8: Aligned TSSOP package outline drawing to JEDEC MO-153. | | | | | | |
| NXB0106_Q100 v.1 | 20230802 | Product data sheet | - | - | | | |

15. Legal information

Data sheet status

| Document status [1][2] | Product status [3] | Definition |
|-----------------------------------|-----------------------|---------------------------------------------------------------------------------------------|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

 Please consult the most recently issued document before initiating or completing a design.

- [2] The term 'short data sheet' is explained in section "Definitions".
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