Dual-supply voltage level translator/transceiver; 3-stateRev. 6.1 — 31 March 2022Product data sheet

1. General description

The 74AVCH1T45 is a single bit, dual supply transceiver that enables bidirectional level translation. The 74AVCH1T45 has active bus hold circuitry which is provided to hold unused or floating data inputs at a valid logic level. This feature eliminates the need for external pull-up or pull-down resistors. The device is fully specified for partial power-down applications using I_{OFF} . The I_{OFF} circuitry disables the output, preventing potentially damaging backflow current through the device when it is powered down.

2. Features and benefits

- Wide supply voltage range from 0.8 V to 3.6 V
- High noise immunity
- CMOS low power dissipation
- Overvoltage tolerant inputs to 3.6 V
- Dynamically controlled outpus
- Complies with JEDEC standards:
 - JESD8-12 (0.8 V to 1.3 V)
 - JESD8-11 (0.9 V to 1.65 V)
 - JESD8-7 (1.65 V to 1.95 V)
 - JESD8-5 (2.3 V to 2.7 V)
 - JESD8C (2.7 V to 3.6 V)
- · ESD protection:
 - HBM JESD22-A114E Class 3B exceeds 8000 V
 - MM JESD22-A115-A exceeds 200 V
 - CDM JESD22-C101C exceeds 1000 V
- Maximum data rates:
 - 500 Mbit/s (1.8 V to 3.3 V translation)
 - 320 Mbit/s (< 1.8 V to 3.3 V translation)
 - 320 Mbit/s (translate to 2.5 V or 1.8 V)
 - 280 Mbit/s (translate to 1.5 V)
 - 240 Mbit/s (translate to 1.2 V)
- Suspend mode
- Bus hold on data inputs
- Latch-up performance exceeds 100 mA per JESD 78 Class II
- Low noise overshoot and undershoot < 10 % of V_{CC}
- I_{OFF} circuitry provides partial Power-down mode operation
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C

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3. Ordering information

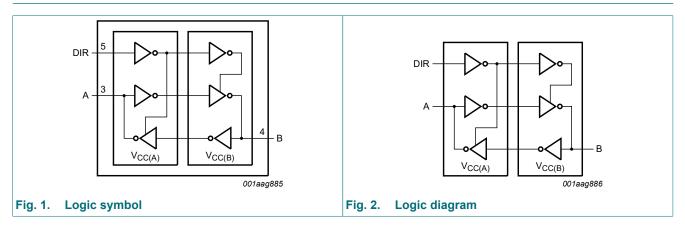
Type number	Package	Package							
	Temperature range	Name	Description	Version					
74AVCH1T45GW	-40 °C to +125 °C	TSSOP6	plastic thin shrink small outline package; 6 leads; body width 1.25 mm	SOT363-2					
74AVCH1T45GM	-40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 × 1.45 × 0.5 mm	SOT886					
74AVCH1T45GN	-40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body 0.9 × 1.0 × 0.35 mm	SOT1115					
74AVCH1T45GS	-40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body 1.0 × 1.0 × 0.35 mm	SOT1202					

4. Marking

Table 2. Marking	
Type number	Marking code [1]
74AVCH1T45GW	К5
74AVCH1T45GM	K5
74AVCH1T45GN	К5
74AVCH1T45GS	K5

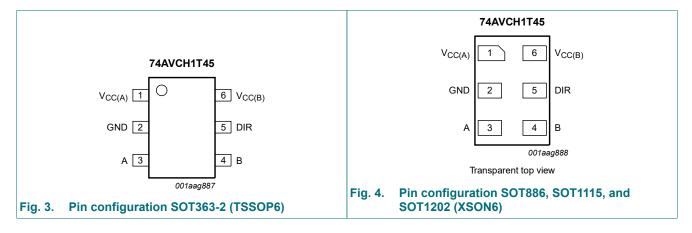
[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.

5. Functional diagram



6. Pinning information

6.1. Pinning



6.2. Pin description

Table 3. Pin description							
Symbol	Pin	Description					
V _{CC(A)}	1	supply voltage port A and DIR					
GND	2	ground (0 V)					
A	3	data input or output					
В	4	data input or output					
DIR	5	direction control					
V _{CC(B)}	6	supply voltage port B					

7. Functional description

Table 4. Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

Supply voltage	Input	Input/output [1]			
V _{CC(A)} , V _{CC(B)}	DIR [2]	A B			
0.8 V to 3.6 V	L	A = B	input		
0.8 V to 3.6 V	Н	input	B = A		
GND [3]	Х	Z	Z		

[1] The input circuit of the data I/O is always active.

[2] [3]

The DIR input circuit is referenced to V_{CC(A)}. If at least one of V_{CC(A)} or V_{CC(B)} is at GND level, the device goes into Suspend mode.

8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

			. –			
Symbol	Parameter	Conditions		Min	Max	Unit
V _{CC(A)}	supply voltage A			-0.5	+4.6	V
V _{CC(B)}	supply voltage B			-0.5	+4.6	V
I _{IK}	input clamping current	V _I < 0 V		-50	-	mA
VI	input voltage		[1]	-0.5	+4.6	V
I _{ОК}	output clamping current	V _O < 0 V		-50	-	mA
Vo	output voltage	Active mode	[1][2][3]	-0.5	V _{CCO} + 0.5	V
		Suspend or 3-state mode	[1]	-0.5	+4.6	V
I _O	output current	$V_{O} = 0 V$ to V_{CCO}		-	±50	mA
I _{CC}	supply current	I _{CC(A)} or I _{CC(B)}		-	100	mA
I _{GND}	ground current			-100	-	mA
T _{stg}	storage temperature			-65	+150	°C
P _{tot}	total power dissipation	T _{amb} = -40 °C to +125 °C	[4]	-	250	mW

[1] The minimum input voltage ratings and output voltage ratings may be exceeded if the input and output current ratings are observed.

[2] V_{CCO} is the supply voltage associated with the output port.

[3] V_{CCO} + 0.5 V should not exceed 4.6 V.

[4] For SOT363-2 (TSSOP6) package: P_{tot} derates linearly with 3.7 mW/K above 83 °C.
 For SOT886 (XSON6) package: P_{tot} derates linearly with 3.3 mW/K above 74 °C.
 For SOT1115 (XSON6) package: P_{tot} derates linearly with 3.2 mW/K above 71 °C.
 For SOT1202 (XSON6) package: P_{tot} derates linearly with 3.3 mW/K above 74 °C.

9. Recommended operating conditions

Table 6. Recommended operating conditions

Symbol	Parameter	Conditions		Min	Max	Unit
V _{CC(A)}	supply voltage A			0.8	3.6	V
V _{CC(B)}	supply voltage B			0.8	3.6	V
VI	input voltage			0	3.6	V
Vo	output voltage	Active mode	[1]	0	V _{CCO}	V
		Suspend or 3-state mode		0	3.6	V
T _{amb}	ambient temperature			-40	+125	°C
Δt/ΔV	input transition rise and fall rate	V _{CCI} = 0.8 V to 3.6 V	[2]	-	5	ns/V

[1] V_{CCO} is the supply voltage associated with the output port.

[2] V_{CCI} is the supply voltage associated with the input port.

10. Static characteristics

Table 7. Typical static characteristics at T_{amb} = 25 °C

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

V_{CCO} is the supply voltage associated with the output port; V_{CCI} is the supply voltage associated with the data input port.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
V _{OH}	HIGH-level output voltage	V _I = V _{IH} or V _{IL}					
		I_{O} = -1.5 mA; $V_{CC(A)}$ = $V_{CC(B)}$ = 0.8 V		-	0.69	-	V
V _{OL} LOW-level output volta		$V_{I} = V_{IH} \text{ or } V_{IL}$					
		I _O = 1.5 mA; V _{CC(A)} = V _{CC(B)} = 0.8 V		-	0.07	-	V
lı	input leakage current	DIR input; $V_I = 0 V \text{ or } 3.6 V$; $V_{CC(A)} = V_{CC(B)} = 0.8 V \text{ to } 3.6 V$	-	±0.025	±0.25	μA	
I _{BHL}	bus hold LOW current	$V_{I} = 0.42 \text{ V}; V_{CC(A)} = V_{CC(B)} = 1.2 \text{ V}$	[1]	-	26	-	μA
I _{BHH}	bus hold HIGH current	$V_{I} = 0.78 V; V_{CC(A)} = V_{CC(B)} = 1.2 V$	[2]	-	-24	-	μA
I _{BHLO}	bus hold LOW overdrive current	$V_I = GND$ to V_{CCI} ; $V_{CC(A)} = V_{CC(B)} = 1.2 V$	[3]	-	28	-	μA
I _{BHHO}	bus hold HIGH overdrive current	$V_I = GND$ to V_{CCI} ; $V_{CC(A)} = V_{CC(B)} = 1.2 V$	[4]	-	-26	-	μA
I _{OZ}	OFF-state output current	A or B port; $V_O = 0$ V or V_{CCO} ; $V_{CC(A)} = V_{CC(B)} = 0.8$ V to 3.6 V	[5]	-	±0.5	±2.5	μA
I _{OFF}	power-off leakage current	A port; V _I or V _O = 0 V to 3.6 V; $V_{CC(A)}$ = 0 V; V _{CC(B)} = 0.8 V to 3.6 V		-	±0.1	±1	μA
		B port; V ₁ or V _O = 0 V to 3.6 V; V _{CC(B)} = 0 V; V _{CC(A)} = 0.8 V to 3.6 V		-	±0.1	±1	μA
CI	input capacitance	DIR input; $V_I = 0 V \text{ or } 3.3 V$; $V_{CC(A)} = V_{CC(B)} = 3.3 V$		-	1.0	-	pF
C _{I/O}	input/output capacitance	A and B port; Suspend mode; $V_O = V_{CCO}$ or GND; $V_{CC(A)} = V_{CC(B)} = 3.3 \text{ V}$		-	4.0	-	pF

[1] The bus hold circuit can sink at least the minimum low sustaining current at V_{IL} max. I_{BHL} should be measured after lowering V_I to GND and then raising it to V_{IL} max.

[2] The bus hold circuit can source at least the minimum high sustaining current at V_{IH} min. I_{BHH} should be measured after raising V_I to V_{CC} and then lowering it to V_{IH} min.

[3] An external driver must source at least ${\sf I}_{\sf BHLO}$ to switch this node from LOW to HIGH.

[4] An external driver must sink at least I_{BHHO} to switch this node from HIGH to LOW.

[5] For I/O ports, the parameter I_{OZ} includes the input leakage current.

Table 8. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V). V_{CCO} is the supply voltage associated with the output port; V_{CCI} is the supply voltage associated with the data input port.

Symbol	Parameter	Conditions	-40 °C te	o +85 °C	-40 °C to +125 °C		
			Min	Max	Min	Max	
V _{IH}	HIGH-level	data input					
	input voltage	V _{CCI} = 0.8 V	0.70V _{CCI}	-	0.70V _{CCI}	-	V
		V _{CCI} = 1.1 V to 1.95 V	0.65V _{CCI}	-	0.65V _{CCI}	-	V
		V _{CCI} = 2.3 V to 2.7 V	1.6	-	1.6	-	V
		V _{CCI} = 3.0 V to 3.6 V	2	-	2	-	V
		DIR input					
		V _{CC(A)} = 0.8 V	0.70V _{CC(A)}	-	0.70V _{CC(A)}	-	V
		V _{CC(A)} = 1.1 V to 1.95 V	0.65V _{CC(A)}	-	0.65V _{CC(A)}	-	V
		V _{CC(A)} = 2.3 V to 2.7 V	1.6	-	1.6	-	V
		V _{CC(A)} = 3.0 V to 3.6 V	2	-	2	-	V
VIL	_OW-level	data input					
	input voltage	V _{CCI} = 0.8 V	-	0.30V _{CCI}	-	0.30V _{CCI}	V
		V _{CCI} = 1.1 V to 1.95 V	-	0.35V _{CCI}	-	0.35V _{CCI}	V
		V _{CCI} = 2.3 V to 2.7 V	-	0.7	-	0.7	V
		V _{CCI} = 3.0 V to 3.6 V	-	0.9	-	0.9	V
		DIR input					
		V _{CC(A)} = 0.8 V	-	0.30V _{CC(A)}	-	0.30V _{CC(A)}	V
		V _{CC(A)} = 1.1 V to 1.95 V	-	0.35V _{CC(A)}	-	0.35V _{CC(A)}	-
		V _{CC(A)} = 2.3 V to 2.7 V	-	0.7	-	0.7	V
		V _{CC(A)} = 3.0 V to 3.6 V	-	0.9	-	0.9	V
V _{он}	HIGH-level	$V_{\rm I} = V_{\rm IH} \text{ or } V_{\rm IL}$					
	output voltage	$I_{O} = -100 \ \mu\text{A};$ $V_{CC(A)} = V_{CC(B)} = 0.8 \ \text{V to } 3.6 \ \text{V}$	V _{CCO} - 0.1	-	V _{CCO} - 0.1	-	V
		$I_{O} = -3 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.1 \text{ V}$	0.85	-	0.85	-	V
		$I_{O} = -6 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.4 \text{ V}$	1.05	-	1.05	-	V
		$I_{O} = -8 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.65 \text{ V}$	1.2	-	1.2	-	V
		$I_{O} = -9 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 2.3 \text{ V}$	1.75	-	1.75	-	V
		$I_{O} = -12 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 3.0 \text{ V}$	2.3	-	2.3	-	V
/ _{OL}	LOW-level	$V_{I} = V_{IH} \text{ or } V_{IL}$					
	output voltage	I _O = 100 μA; V _{CC(A)} = V _{CC(B)} = 0.8 V to 3.6 V	-	0.1	-	0.1	V
		$I_{O} = 3 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.1 \text{ V}$	-	0.25	-	0.25	V
		$I_{O} = 6 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.4 \text{ V}$	-	0.35	-	0.35	V
		$I_{O} = 8 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.65 \text{ V}$	-	0.45	-	0.45	V
		$I_{O} = 9 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 2.3 \text{ V}$	-	0.55	-	0.55	V
		$I_{O} = 12 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 3.0 \text{ V}$	-	0.7	-	0.7	V
I	input leakage current	DIR input; $V_I = 0 V \text{ or } 3.6 V$; $V_{CC(A)} = V_{CC(B)} = 0.8 V \text{ to } 3.6 V$	-	±1	-	±1.5	μA

Dual-supply voltage level translator/transceiver; 3-state

Symbol	Parameter	Conditions	-40 °C t	o +85 °C	-40 °C to +125 °C		Unit
		-	Min	Max	Min	Max	_
I _{BHL}	bus hold LOW	A or B port [1]					
	current	V _I = 0.49 V; V _{CC(A)} = V _{CC(B)} = 1.4 V	15	-	15	-	μA
		V _I = 0.58 V; V _{CC(A)} = V _{CC(B)} = 1.65 V	25	-	25	-	μA
		V _I = 0.70 V; V _{CC(A)} = V _{CC(B)} = 2.3 V	45	-	45	-	μA
		V _I = 0.80 V; V _{CC(A)} = V _{CC(B)} = 3.0 V	100	-	90	-	μA
I _{BHH}	bus hold HIGH	A or B port [2]					
	current	V _I = 0.91 V; V _{CC(A)} = V _{CC(B)} = 1.4 V	-15	-	-15	-	μA
		V _I = 1.07 V; V _{CC(A)} = V _{CC(B)} = 1.65 V	-25	-	-25	-	μA
		V _I = 1.60 V; V _{CC(A)} = V _{CC(B)} = 2.3 V	-45	-	-45	-	μA
		V _I = 2.00 V; V _{CC(A)} = V _{CC(B)} = 3.0 V	-100	-	-100	-	μA
I _{BHLO}	bus hold LOW overdrive current	A or B port [3]					
		$V_{CC(A)} = V_{CC(B)} = 1.6 V$	125	-	125	-	μA
		V _{CC(A)} = V _{CC(B)} = 1.95 V	200	-	200	-	μA
		$V_{CC(A)} = V_{CC(B)} = 2.7 V$	300	-	300	-	μA
		$V_{CC(A)} = V_{CC(B)} = 3.6 V$	500	-	500	-	μA
I _{BHHO}	bus hold HIGH	A or B port [4]					
	overdrive current	$V_{CC(A)} = V_{CC(B)} = 1.6 V$	-125	-	-125	-	μA
	current	V _{CC(A)} = V _{CC(B)} = 1.95 V	-200	-	-200	-	μA
		$V_{CC(A)} = V_{CC(B)} = 2.7 V$	-300	-	-300	-	μA
		$V_{CC(A)} = V_{CC(B)} = 3.6 V$	-500	-	-500	-	μA
I _{OZ}	OFF-state output current	A or B port; $V_O = 0 V \text{ or } V_{CCO}$; [5] $V_{CC(A)} = V_{CC(B)} = 0.8 V \text{ to } 3.6 V$	-	±5	-	±7.5	μA
I _{OFF}	power-off leakage current	A port; V_1 or $V_0 = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0.8$ V to 3.6 V	-	±5	-	±35	μA
		B port; V ₁ or V ₀ = 0 V to 3.6 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0.8$ V to 3.6 V	-	±5	-	±35	μA

Symbol	Parameter	Conditions	-40 °C t	o +85 °C	-40 °C to	o +125 °C	Unit
			Min	Max	Min	Max	
I _{CC}	supply current	A port; $V_I = 0$ V or V_{CCI} ; $I_O = 0$ A					
		$V_{CC(A)} = 0.8 V \text{ to } 3.6 V;$ $V_{CC(B)} = 0.8 V \text{ to } 3.6 V$	-	8	-	12	μA
		V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V	-	8	-	12	μA
		V _{CC(A)} = 0 V; V _{CC(B)} = 3.6 V	-2	-	-8	-	μA
		B port; $V_I = 0$ V or V_{CCI} ; $I_O = 0$ A					
		$V_{CC(A)} = 0.8 V \text{ to } 3.6 V;$ $V_{CC(B)} = 0.8 V \text{ to } 3.6 V$	-	8	-	12	μA
		V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V	-2	-	-8	-	μA
		V _{CC(A)} = 0 V; V _{CC(B)} = 3.6 V	-	8	-	12	μA
		A plus B port ($I_{CC(A)} + I_{CC(B)}$); $I_O = 0 A$; $V_I = 0 V \text{ or } V_{CCI}$; $V_{CC(A)} = 0.8 V \text{ to } 3.6 V$; $V_{CC(B)} = 0.8 V \text{ to } 3.6 V$	-	16	-	24	μA

[1] The bus hold circuit can sink at least the minimum low sustaining current at V_{IL} max. I_{BHL} should be measured after lowering V_I to GND and then raising it to V_{IL} max. The bus hold circuit can source at least the minimum high sustaining current at V_{IH} min. I_{BHH} should be measured after raising V_I to

[2] V_{CC} and then lowering it to V_{IH} min.

An external driver must source at least $\mathsf{I}_{\mathsf{BHLO}}$ to switch this node from LOW to HIGH. [3]

An external driver must sink at least $\mathsf{I}_{\mathsf{BHHO}}$ to switch this node from HIGH to LOW. [4]

For I/O ports, the parameter I_{OZ} includes the input leakage current. [5]

11. Dynamic characteristics

Table 9. Typical dynamic characteristics at V_{CC(A)} = 0.8 V and T_{amb} = 25 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6. t_{pd} is the same as t_{PLH} and t_{PHL} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} ; t_{en} is the same as t_{PZL} and t_{PZH} .

ten is a calculated value using the formula shown in Section 12.4.

Symbol	Parameter	Conditions	V _{CC(B)}						Unit
			0.8 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	
t _{pd}	propagation delay	A to B	15.8	8.4	8.0	8.0	8.7	9.5	ns
		B to A	15.8	12.7	12.4	12.2	12.0	11.8	ns
t _{dis}	disable time	DIR to A	12.2	12.2	12.2	12.2	12.2	12.2	ns
		DIR to B	11.7	7.9	7.6	8.2	8.7	10.2	ns
t _{en}	enable time	DIR to A	27.5	20.6	20.0	20.4	20.7	22.0	ns
		DIR to B	28.0	20.6	20.2	20.2	20.9	21.7	ns

Table 10. Typical dynamic characteristics at $V_{CC(B)}$ = 0.8 V and T_{amb} = 25 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6. t_{pd} is the same as t_{PLH} and t_{PHL} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} ; t_{en} is the same as t_{PZL} and t_{PZH} . ten is a calculated value using the formula shown in Section 12.4.

Symbol	mbol Parameter Conditions V _{CC(A)}						Unit		
			0.8 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	
t _{pd}	propagation delay	A to B	15.8	12.7	12.4	12.2	12.0	11.8	ns
		B to A	15.8	8.4	8.0	8.0	8.7	9.5	ns
t _{dis}	disable time	DIR to A	12.2	4.9	3.8	3.7	2.8	3.4	ns
		DIR to B	11.7	9.2	9.0	8.8	8.7	8.6	ns
t _{en}	enable time	DIR to A	27.5	17.6	17.0	16.8	17.4	18.1	ns
		DIR to B	28.0	17.6	16.2	15.9	14.8	15.2	ns

Table 11. Typical power dissipation capacitance at V_{CC(A)} = V_{CC(B)} and T_{amb} = 25 °C

Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	$V_{CC(A)}$ and $V_{CC(B)}$						
			0.8 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	
C _{PD}	power dissipation capacitance	A port: (direction A to B); [1][2] B port: (direction B to A)	1	2	2	2	2	2	pF
		A port: (direction B to A); [1][2] B port: (direction A to B)	9	11	11	12	14	17	pF

[1] C_{PD} is used to determine the dynamic power dissipation (P_D in μW).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$ where: f_i = input frequency in MHz; f_o = output frequency in MHz;

C_L = load capacitance in pF;

 V_{CC} = supply voltage in V;

N = number of inputs switching; $\Sigma(C_L \times V_{CC}^2 \times f_o) = sum of the outputs.$ [2] $f_i = 10 \text{ MHz}; V_I = \text{GND to } V_{CC}; t_r = t_f = 1 \text{ ns}; C_L = 0 \text{ pF}; R_L = \infty \Omega.$

Table 12. Dynamic characteristics for temperature range -40 °C to +85 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6. t_{pd} is the same as t_{PLH} and t_{PHL} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} ; t_{en} is the same as t_{PZL} and t_{PZH} . t_{en} is a calculated value using the formula shown in Section 12.4.

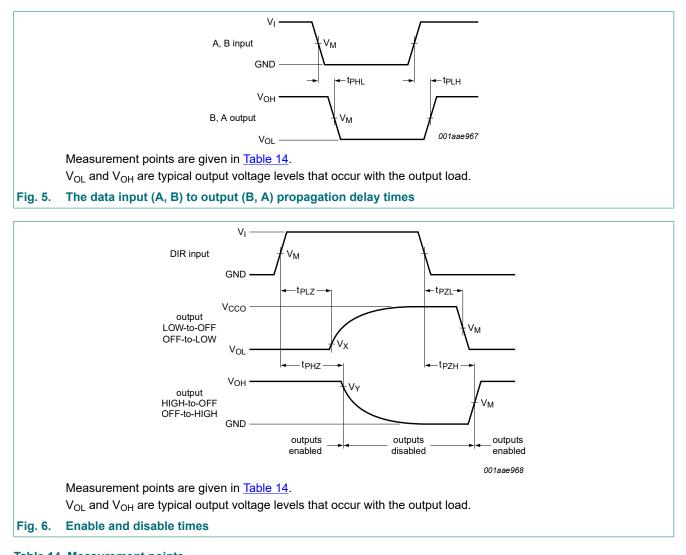
Symbol	Parameter	Conditions	V _{CC(B)}								Unit		
			1.2 V ± 0.1 V		1.5 V :	± 0.1 V		: 0.15 V	2.5 V	± 0.2 V	3.3 V :	± 0.3 V	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
V _{CC(A)} =	1.1 V to 1.3 V						1	1					1
t _{pd}	propagation	A to B	1.0	9.0	0.7	6.8	0.6	6.1	0.5	5.7	0.5	6.1	ns
	delay	B to A	1.0	9.0	0.8	8.0	0.7	7.7	0.6	7.2	0.5	7.1	ns
t _{dis}	disable time	DIR to A	2.2	8.8	2.2	8.8	2.2	8.8	2.2	8.8	2.2	8.8	ns
		DIR to B	2.2	8.4	1.8	6.7	2.0	6.9	1.7	6.2	2.4	7.2	ns
t _{en}	enable time	DIR to A	-	17.4	-	14.7	-	14.6	-	13.4	-	14.3	ns
		DIR to B	-	17.8	-	15.6	-	14.9	-	14.5	-	14.9	ns
V _{CC(A)} =	1.4 V to 1.6 V		1		I	1	1				1	1	1
t _{pd}	propagation	A to B	1.0	8.0	0.7	5.4	0.6	4.6	0.5	3.7	0.5	3.5	ns
	delay	B to A	1.0	6.8	0.8	5.4	0.7	5.1	0.6	4.7	0.5	4.5	ns
t _{dis}	lis disable time	DIR to A	1.6	6.3	1.6	6.3	1.6	6.3	1.6	6.3	1.6	6.3	ns
		DIR to B	2.0	7.6	1.8	5.9	1.6	6.0	1.2	4.8	1.7	5.5	ns
t _{en} enable time	enable time	DIR to A	-	14.4	-	11.3	-	11.1	-	9.5	-	10.0	ns
		DIR to B	-	14.3	-	11.7	-	10.9	-	10.0	-	9.8	ns
V _{CC(A)} =	1.65 V to 1.95	V					1	1					-
t _{pd} propagation delay	propagation	A to B	1.0	7.7	0.6	5.1	0.5	4.3	0.5	3.4	0.5	3.1	ns
	B to A	1.0	6.1	0.7	4.6	0.5	4.4	0.5	3.9	0.5	3.7	ns	
t _{dis}	disable time	DIR to A	1.6	5.5	1.6	5.5	1.6	5.5	1.6	5.5	1.6	5.5	ns
		DIR to B	1.8	7.8	1.8	5.7	1.4	5.8	1.0	4.5	1.5	5.2	ns
t _{en}	enable time	DIR to A	-	13.9	-	10.3	-	10.2	-	8.4	-	8.9	ns
		DIR to B	-	13.2	-	10.6	-	9.8	-	8.9	-	8.6	ns
V _{CC(A)} =	2.3 V to 2.7 V		1		I	1	1			1	1	1	1
t _{pd}	propagation	A to B	1.0	7.2	0.5	4.7	0.5	3.9	0.5	3.0	0.5	2.6	ns
	delay	B to A	1.0	5.7	0.6	3.8	0.5	3.4	0.5	3.0	0.5	2.8	ns
t _{dis}	disable time	DIR to A	1.5	4.2	1.5	4.2	1.5	4.2	1.5	4.2	1.5	4.2	ns
		DIR to B	1.7	7.3	2.0	5.2	1.5	5.1	0.6	4.2	1.1	4.8	ns
t _{en}	enable time	DIR to A	-	13.0	-	9.0	-	8.5	-	7.2	-	7.6	ns
		DIR to B	-	11.4	-	8.9	-	8.1	-	7.2	-	6.8	ns
V _{CC(A)} =	3.0 V to 3.6 V		1		I	1	1	1		1	1	1	1
t _{pd}	propagation	A to B	1.0	7.1	0.5	4.5	0.5	3.7	0.5	2.8	0.5	2.4	ns
	delay	B to A	1.0	6.1	0.6	3.6	0.5	3.1	0.5	2.6	0.5	2.4	ns
t _{dis}	disable time	DIR to A	1.5	4.7	1.5	4.7	1.5	4.7	1.5	4.7	1.5	4.7	ns
		DIR to B	1.7	7.2	0.7	5.5	0.6	5.5	0.7	4.1	1.7	4.7	ns
t _{en}	enable time	DIR to A	-	13.3	-	9.1	-	8.6	-	6.7	-	7.1	ns
		DIR to B	-	11.8	-	9.2	-	8.4	-	7.5	-	7.1	ns

Table 13. Dynamic characteristics for temperature range -40 °C to +125 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6. t_{pd} is the same as t_{PLH} and t_{PHL} ; t_{dis} is the same as t_{PLZ} and t_{PHZ} ; t_{en} is the same as t_{PZL} and t_{PZH} . t_{en} is a calculated value using the formula shown in Section 12.4.

Symbol	Parameter	Conditions	V _{CC(B)}								Unit		
			1.2 V ± 0.1 V		1.5 V :	± 0.1 V		: 0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
V _{CC(A)} =	1.1 V to 1.3 V				I			1					
t _{pd}	propagation	A to B	1.0	9.9	0.7	7.5	0.6	6.8	0.5	6.3	0.5	6.8	ns
	delay	B to A	1.0	9.9	0.8	8.8	0.7	8.5	0.6	8.0	0.5	7.9	ns
t _{dis}	disable time	DIR to A	2.2	9.7	2.2	9.7	2.2	9.7	2.2	9.7	2.2	9.7	ns
		DIR to B	2.2	9.2	1.8	7.4	2.0	7.6	1.7	6.9	2.4	8.0	ns
t _{en}	enable time	DIR to A	-	19.1	-	16.2	-	16.1	-	14.9	-	15.9	ns
		DIR to B	-	19.6	-	17.2	-	16.5	-	16.0	-	16.5	ns
V _{CC(A)} =	1.4 V to 1.6 V			1	I	1	1	1				1	1
t _{pd}	propagation	A to B	1.0	8.8	0.7	6.0	0.6	5.1	0.5	4.1	0.5	3.9	ns
	delay	B to A	1.0	7.5	0.8	6.0	0.7	5.7	0.6	5.2	0.5	5.0	ns
t _{dis}	s disable time	DIR to A	1.6	7.0	1.6	7.0	1.6	7.0	1.6	7.0	1.6	7.0	ns
		DIR to B	2.0	8.3	1.8	6.5	1.6	6.6	1.2	5.3	1.7	6.1	ns
t _{en}	enable time	DIR to A	-	15.8	-	12.5	-	12.3	-	10.5	-	11.1	ns
		DIR to B	-	15.8	-	13.0	-	12.7	-	11.1	-	10.9	ns
V _{CC(A)} =	1.65 V to 1.95	V											-
t _{pd}	propagation	A to B	1.0	8.5	0.6	5.7	0.5	4.8	0.5	3.8	0.5	3.5	ns
delay	delay	B to A	1.0	6.8	0.7	5.1	0.5	4.9	0.5	4.3	0.5	4.1	ns
t _{dis}	disable time	DIR to A	1.6	6.1	1.6	6.1	1.6	6.1	1.6	6.1	1.6	6.1	ns
		DIR to B	1.8	8.6	1.8	6.3	1.4	6.4	1.0	5.0	1.5	5.8	ns
t _{en}	enable time	DIR to A	-	15.4	-	11.4	-	11.3	-	9.3	-	9.9	ns
		DIR to B	-	14.6	-	11.8	-	10.9	-	9.9	-	9.6	ns
V _{CC(A)} =	2.3 V to 2.7 V												
t _{pd}	propagation	A to B	1.0	8.0	0.5	5.2	0.5	4.3	0.5	3.3	0.5	2.9	ns
	delay	B to A	1.0	6.3	0.6	4.2	0.5	3.8	0.5	3.3	0.5	3.1	ns
t _{dis}	disable time	DIR to A	1.5	4.7	1.5	4.7	1.5	4.7	1.5	4.7	1.5	4.7	ns
		DIR to B	1.7	8.0	2.0	5.8	1.5	5.7	0.6	4.7	1.1	5.3	ns
t _{en}	enable time	DIR to A	-	14.3	-	10.0	-	9.5	-	8.0	-	8.4	ns
		DIR to B	-	12.7	-	9.9	-	9.0	-	8.0	-	7.6	ns
$V_{CC(A)} =$	3.0 V to 3.6 V		1	1	I	1	1	1	<u> </u>			1	1
t _{pd}	propagation	A to B	1.0	7.9	0.5	5.0	0.5	4.1	0.5	3.1	0.5	2.7	ns
	delay	B to A	1.0	6.8	0.6	4.0	0.5	3.5	0.5	2.9	0.5	2.7	ns
t _{dis}	disable time	DIR to A	1.5	5.2	1.5	5.2	1.5	5.2	1.5	5.2	1.5	5.2	ns
		DIR to B	1.7	7.9	0.7	6.0	0.6	6.1	0.7	4.6	1.7	5.2	ns
t _{en}	enable time	DIR to A	-	14.7	-	10.1	-	9.6	-	7.5	-	7.9	ns
		DIR to B	-	13.1	_	10.2	-	9.3	-	8.3	-	7.9	ns

11.1. Waveforms and test circuit



Supply voltage	Input [1]	Output [2]	Output [2]			
V _{CC(A)} , V _{CC(B)}	V _M	V _M	V _X	V _Y		
1.1 V to 1.6 V	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.1 V	V _{OH} - 0.1 V		
1.65 V to 2.7 V	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.15 V	V _{OH} - 0.15 V		
3.0 V to 3.6 V	0.5V _{CCI}	0.5V _{CCO}	V _{OL} + 0.3 V	V _{OH} - 0.3 V		

[1] V_{CCI} is the supply voltage associated with the data input port.

[2] V_{CCO} is the supply voltage associated with the output port.

Dual-supply voltage level translator/transceiver; 3-state

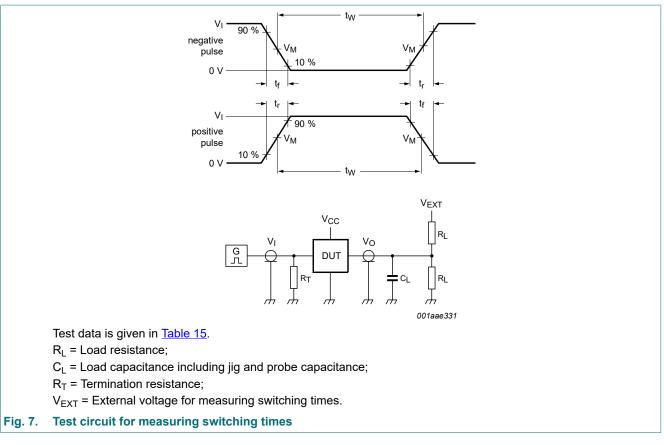


Table 15. Test data

Supply voltage Input		Load		V _{EXT}			
$V_{CC(A)}, V_{CC(B)}$	V _I [1]	Δt/ΔV	CL	RL	t _{PLH} , t _{PHL}	t _{PZH} , t _{PHZ}	t _{PZL} , t _{PLZ} [2]
1.1 V to 1.6 V	V _{CCI}	≤ 1.0 ns/V	15 pF	2 kΩ	open	GND	2V _{CCO}
1.65 V to 2.7 V	V _{CCI}	≤ 1.0 ns/V	15 pF	2 kΩ	open	GND	2V _{CCO}
3.0 V to 3.6 V	V _{CCI}	≤ 1.0 ns/V	15 pF	2 kΩ	open	GND	2V _{CCO}

[1] V_{CCI} is the supply voltage associated with the data input port.

[2] V_{CCO} is the supply voltage associated with the output port.

74AVCH1T45

12. Application information

12.1. Unidirectional logic level-shifting application

The circuit given in Fig. 8 is an example of the 74AVCH1T45 being used in a unidirectional logic level-shifting application.

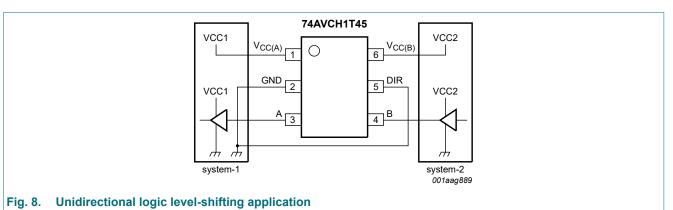


Table '	Table 16. Description unidirectional logic level-shifting application							
Pin	Name	Function	Description					
1	V _{CC(A)}	V _{CC1}	supply voltage of system-1 (0.8 V to 3.6 V)					
2	GND	GND	device GND					
3	A	OUT	output level depends on V _{CC1} voltage					
4	В	IN	input threshold value depends on V _{CC2} voltage					
5	DIR	DIR	the GND (LOW level) determines B port to A port direction					
6	V _{CC(B)}	V _{CC2}	supply voltage of system-2 (0.8 V to 3.6 V)					

12.2. Bidirectional logic level-shifting application

Fig. 9 shows the 74AVCH1T45 being used in a bidirectional logic level-shifting application. Since the device does not have an output enable pin, the system designer should take precautions to avoid bus contention between system-1 and system-2 when changing directions.

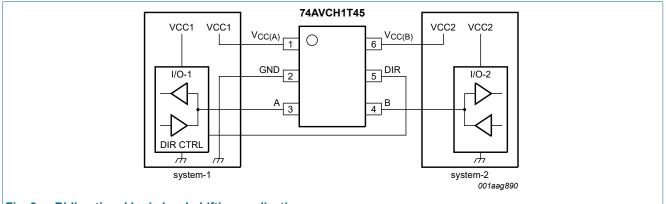


Fig. 9. Bidirectional logic level-shifting application

<u>Table 17</u> gives a sequence that will illustrate data transmission from system-1 to system-2 and then from system-2 to system-1.

74AVCH1T45

Table 17. Description bidirectional logic level-shifting application

H = HIGH voltage level; L = LOW voltage level; Z = high-impedance OFF-state.

State	DIR CTRL	I/O-1	I/O-2	Description
1	Н	output	input	system-1 data to system-2
2	Н	Z	Z	system-2 is getting ready to send data to system-1. I/O-1 and I/O-2 are disabled. The bus-line state depends on bus hold.
3	L	Z	Z	DIR bit is set LOW. I/O-1 and I/O-2 still are disabled. The bus-line state depends on bus hold.
4	L	input	output	system-2 data to system-1

12.3. Power-up considerations

The device is designed such that no special power-up sequence is required other than GND being applied first.

Table 18. Typical total supply current (I_{CC(A)} + I_{CC(B)})

V _{CC(A)}	V _{CC(B)}									
	0 V	0.8 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V			
0 V	0	0.1	0.1	0.1	0.1	0.1	0.1	μA		
0.8 V	0.1	0.1	0.1	0.1	0.1	0.7	2.3	μA		
1.2 V	0.1	0.1	0.1	0.1	0.1	0.3	1.4	μA		
1.5 V	0.1	0.1	0.1	0.1	0.1	0.1	0.9	μA		
1.8 V	0.1	0.1	0.1	0.1	0.1	0.1	0.5	μA		
2.5 V	0.1	0.7	0.3	0.1	0.1	0.1	0.1	μA		
3.3 V	0.1	2.3	1.4	0.9	0.5	0.1	0.1	μA		

12.4. Enable times

The enable times for the 74AVCH1T45 are calculated from the following formulas:

 t_{en} (DIR to A) = t_{dis} (DIR to B) + t_{pd} (B to A)

 t_{en} (DIR to B) = t_{dis} (DIR to A) + t_{pd} (A to B)

In a bidirectional application, these enable times provide the maximum delay from the time the DIR bit is switched until an output is expected. For example, if the 74AVCH1T45 initially is transmitting from A to B, then the DIR bit is switched, the B port of the device must be disabled before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay.

13. Package outline

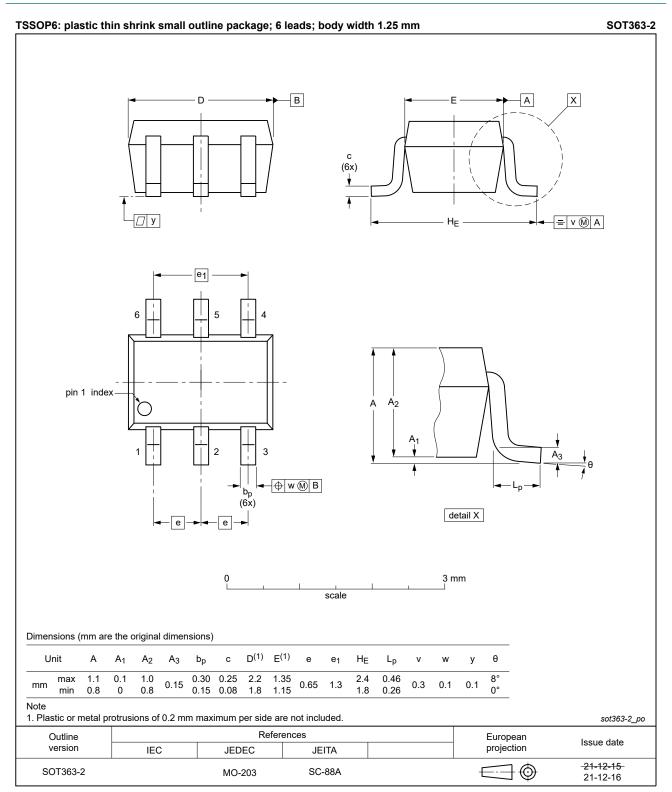


Fig. 10. Package outline SOT363-2 (TSSOP6)

Dual-supply voltage level translator/transceiver; 3-state

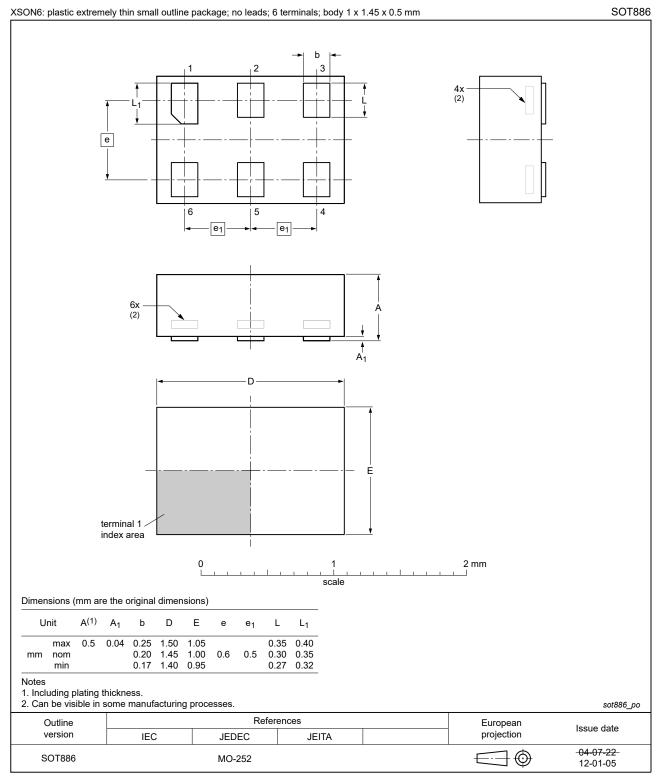


Fig. 11. Package outline SOT886 (XSON6)

Dual-supply voltage level translator/transceiver; 3-state

XSON6: extremely thin small outline package; no leads; 6 terminals; body 0.9 x 1.0 x 0.35 mm

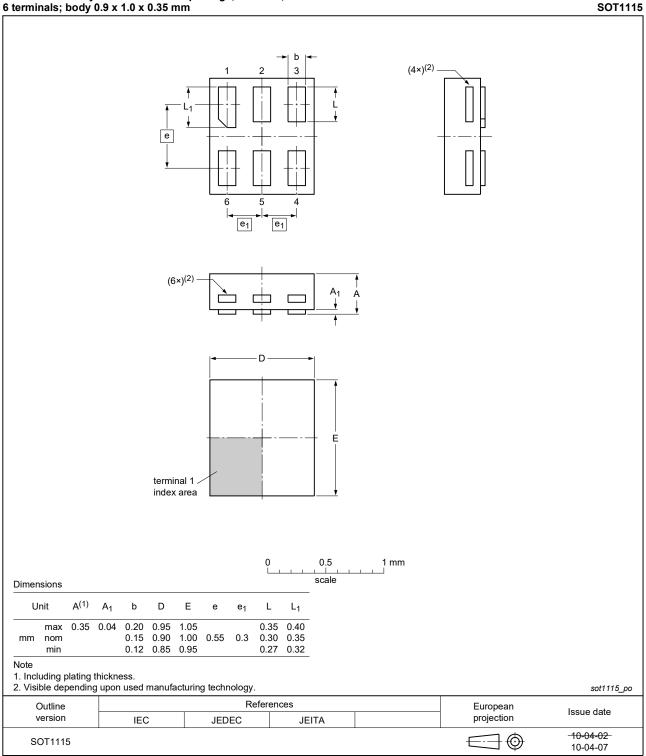


Fig. 12. Package outline SOT1115 (XSON6)

Dual-supply voltage level translator/transceiver; 3-state

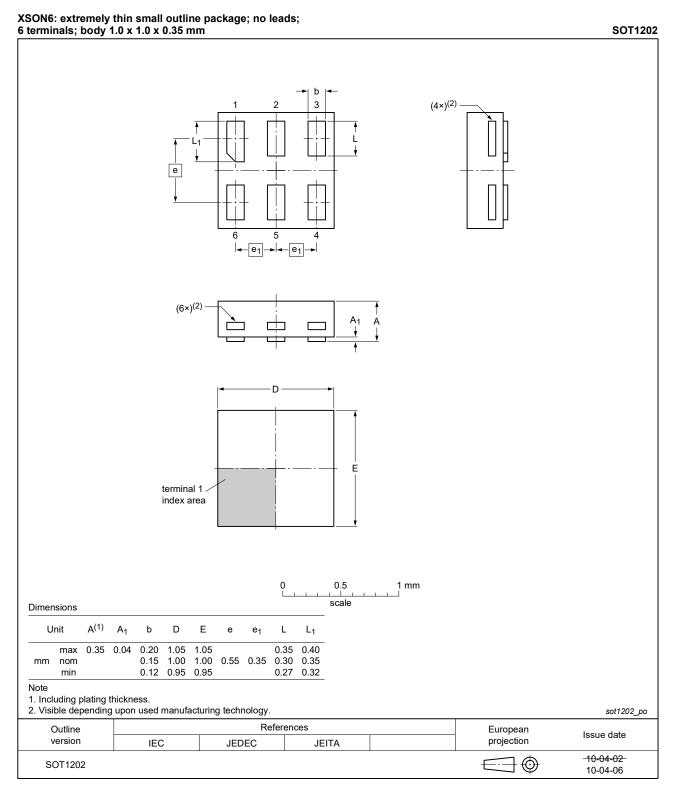


Fig. 13. Package outline SOT1202 (XSON6)

14. Abbreviations

Acronym	Description
CDM	Charged Device Model
CMOS	Complementary Metal Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
MM	Machine Model

15. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
74AVCH1T45 v.6.1	20220331	Product data sheet	-	74AVCH1T45 v.5
Modifications:	Nexperia. • Legal texts ha • <u>Section 1</u> and • Package SOT	this data sheet has been in we been adapted to the ne <u>Section 2</u> updated. 363 (SC-88) changed to S ing values for P _{tot} total po	ew company name where	
74AVCH1T45 v.5	20160106	Product data sheet	-	74AVCH1T45 v.4
Modifications:	• <u>Table 16</u> : Lab	els for pins 4 and 5 correc	ted.	
74AVCH1T45 v.4	20120803	Product data sheet	-	74AVCH1T45 v.3
Modifications:	Package outli	ne drawing of SOT886 (Fi	g. <u>11</u>) modified.	/
74AVCH1T45 v.3	20111027	Product data sheet	-	74AVCH1T45 v.2
Modifications:		umber 74AVCH1T45GN (S umber 74AVCH1T45GS (S		
74AVCH1T45 v.2	20090505	Product data sheet	-	74AVCH1T45 v.1
74AVCH1T45 v.1	20071025	Product data sheet	-	-

16. Legal information

Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

 Please consult the most recently issued document before initiating or completing a design.

- [2] The term 'short data sheet' is explained in section "Definitions".
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the internet at <u>https://www.nexperia.com</u>.

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